Positional Concern and Low Demand for Redistribution of the Poor*

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Abstract

The two observations that (1) some low-income citizens demand low redistribution and (2) as income inequality becomes more severe a larger proportion of citizens make less demand for redistribution (Kelly and Enns (2010)) are counter-intuitive because people oppose redistribution that could be beneficial to them. Understanding the main driving factor that leads to the economic conservatism of the poor is crucial: it guides how policymakers should design redistribution. I show that positional concern can be one of these main factors. When citizens care about their relative position on consumption and their labor productivity is slightly perturbed when a new tax policy is implemented, only middle-income citizens may vote for redistribution. Compared with the prospect of upward mobility hypothesis, I provide a testable prediction for the relationship between economic inequality and the economic conservatism of the poor. If positional concern is the main driving factor, policymakers should focus on increasing the low-income citizens’ standard of living to the middle class; and if the prospect of upward mobility is the main factor then they should focus on minimizing income gaps.

Keywords: economic conservatism; economic inequality; redistribution; externality; positional concern

JEL Classification: C72, D72

1 Introduction

My research questions originate from Kelly and Enns (2010) who reported that the more severe income inequality is, the more inclined the poor are to oppose redistribu-
Why are some of the poor economically conservative? Why do more of the poor demand less redistribution when income inequality becomes more severe? These observations are a bit of a conundrum because economic models, such as Meltzer and Richard (1981) that assume self-interested rational agents, typically predict that anyone whose income or productivity is below that of a decisive voter should vote for redistribution; and that more severe income inequality, which leads to a larger gap between median income and mean income, raises social demand for redistribution. Even if we understand the higher income earners’ support for redistribution by taking into account some types of social preferences (such as altruism and/or inequity aversion), it is still hard to explain the lower income citizens’ low demand for redistribution. Understanding the main driving factor that leads to the economic conservatism of the poor is important for policymakers in that it could affect the desirable form of economic redistribution. Thus, the primary purpose of this research is to answer the following question: What can policymakers who deal with economic inequality learn from the changes in economic conservatism of the poor?

There are several studies that address the economic conservatism of the poor. These are discussed in detail in subsection 1.1. The main contribution of this paper is to provide an additional attribute that has not been explored well but which significantly helps us to understand the low demand for redistribution by the poor. I provide a stripped-down model that yields the following two predictions: (1) The poor and the rich oppose a proposed redistribution policy that offers some help to the poor and only the middle supports it (henceforth this is called ‘the observation’) and (2) as income inequality gets more severe, the economic conservatism of the poor becomes more pervasive (this is called ‘the dynamics’).

Specifically, I consider a continuum of workers whose labor productivity (type) is low, middle, and high. Each worker compares his or her indirect utility under a “laissez-faire” economy with that of an economy that has an income tax rate of \( t \in (0, 1) \) and a lump-sum transfer. Although I believe that concern for a future generation’s welfare would enable us to describe the dynamics across generations, and the coexistence of labor and capi-

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1 According to Gallup’s Economy and Personal Finance survey on April 9–12, 2015, 35% of respondents whose household income was under $30,000 answered that the government should not redistribute wealth by heavy taxes on the rich. “Americans Continue to Say U.S. Wealth Distribution Is Unfair”. gallup.com. Access: 10/8/2015.

2 Some of the primitive ideas, not the main contributions, appeared in a more preliminary form in Kim and Choi (2015).

3 A more relevant and realistic observation that we should try to understand may be that citizens whose income or productivity is below that of the decisive voter do not form a consensus on redistribution. For example, Kenworthy and McCall (2008) found that the median-voter hypothesis was not supported over time in eight nations during the 1980s and 1990s. The model considered here serves as one possible solution with two critical reversal points regarding public opinion about redistribution, rather than one.
tal income earners would help us to understand interactions between classes, I consider neither the overlapping generation nor capitalists, on purpose, to focus on how public opinion on the redistribution policy for the current generation is formed while shutting down all other possible channels. Within this model, my goals are reduced to (1) showing a reasonable set of assumptions that predicts ‘the observation,’ and (2) examining whether a larger set of parameters predicts ‘the dynamics’ within such assumptions. This approach is parsimonious in the sense that it does neither consider exogenous preferences over political parties nor heterogeneous beliefs about the state of the world and the state of themselves. It also allows better comparative statistics.

To capture economic mobility positively associated with the policy changes (Chetty et al., 2014), I assume citizens’ productivity is slightly perturbed only if a new policy is implemented. Then, positional concern would play a role to explain both ‘the observation’ and ‘the dynamics.’ By positional concern, I mean that citizens care about their relative position in a ranking based on consumption. Even if a redistribution policy allows the poor to enjoy more resources for consumption in absolute terms, some of the poor may have a relatively smaller amount of resources compared with others who previously had the same amount under the status quo policy. If the expected marginal disutility by positional concern exceeds the marginal utility from redistribution, they prefer to stay with the status quo. The rich prefer the status quo because under a new redistribution policy their resources decrease in absolute terms, and for some of them, decrease in relative terms, too. The middle-income group may prefer the new policy under a reasonable assumption about utility from the relative rank.

The last-place aversion (LPA) reported by Kuziemko et al. (2014) is one of the key assumptions I rely on. If a last-place-averse citizen is concerned about his or her relative position, in general, then the marginal disutility of moving down from second-to-the-bottom to the very bottom must be strictly greater than that of moving down from third-to-the-bottom to second-to-the-bottom. Thus, the utility function that captures the positional concern should be increasingly concave in position.

Another contribution of this paper is to provide a way to find the desirable form of redistribution policy by observing the changes in public opinion about redistribution. I show that if positional concern is the main driving force behind the economic conser-

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4 Although I assume a minuscule productivity shock for parsimonious representation of the model, it doesn’t necessarily have to be a ‘productivity’ shock in particular. Any random component that could cause a chance of economic mobility will also work.

5 In the sense that one’s consumption affects the others’ utility, positional concern is always associated with (negative) positional externality. In this paper, I interchangeably use ‘positional concern’ and ‘positional externality’ in relevant contexts.

6 This increasingly concave function plays an important role as does the increasingly concave mobility function considered in Benabou and Ok (2001). I discuss it in greater detail in Section 4.
vatism of the poor, then the right skewness of income distribution is positively related to
the increased economic conservatism of the low-income group, while the increase in the
income gap between groups is negatively related to it. The prospect of upward mobility
works in the opposite way: If the low-income citizens believe that opposing redistribution
will be beneficial for them in the future, the right skewness of income distribution will
negatively affect the economic conservatism of the poor, while the increase in the income
gap between groups is positively related to it. Thus, if positional concern is the main
driving factor, utilitarian policymakers should focus more on increasing the low-income
citizens’ standard of living to the middle class; if the prospect of upward mobility is the
main factor, minimizing income gaps by cutting down the top-income earnings could be
of their primary interest.

The rest of this paper is organized as follows: In the following subsection, I review
related studies. Section 2 describes economic models and some results from those mod-
els, Section 3 shows the dynamics of the model, and Section 4 discusses the relationship
between the model and the prospect of upward mobility hypothesis and possibility of con-
ducting empirical and experimental follow-up studies. Section 5 summarizes the lessons
from this project. Omitted proofs are in the Appendix.

1.1 Related Literature

Since Thorstein Veblen (1899) addressed the low demand for redistribution by the
poor, and the economic conservatism of the poor in a broader sense, a number of possible
explanations have been offered for the economic conservatism of the poor. The prospect
of upward mobility may make the low-income citizens believe that opposing redistribu-
tion will bring economic prosperity and eventually will be beneficial for them (Benabou
and Ok, 2001). Biased perceptions in individuals’ evaluations of their own relative po-
sitions in the income distribution drive the low-income citizens (who mistakenly believe
they are middle-income) to demand redistribution less (Cruces et al., 2013). Hetero-
genous beliefs about intergenerational mobility could affect preferences for redistribu-
tion (Alesina et al., 2018), and heterogeneous social capital measured by participation in
community activities is also associated with preferences for redistribution (Yamamura,
2012). The public may be following how the media covers household-income inequality
and how this relates to the government, as opposed to the inequality itself (Kelly
and Enns, 2010). Distrust of the entire political system, doubts about the government’s
efficiency, and cynicism about redistribution may prevent the poor from being liberal
(Houtman et al., 2008). The underprivileged who lack self-esteem may prefer to iden-
tify themselves as belonging to a group (in this context, a state or a country), and this
tendency may encourage them to support the conservative political party that advocates
economic prosperity rather than economic equality. Some may look for specific reasons for the lower income group’s social and cultural conservatism applied to a specific region (Frank, 2004) or religion (Guiso et al., 2003), but there is no clear linkage between social and cultural conservatism and economic conservatism. It may also be possible that the public has a lexicographical preference for government policies, so that public opinion about redistribution may be influenced by other issues. For example, the poor may decide to vote for a political party that offers a preferred policy about, say, guns or abortion, and the party may happen to be against a redistribution policy. I admit that all aforementioned explanations have their merits and view this study as a complement to the existing arguments.

Veblen (1899) claims that implementing a new redistribution policy may give rise to some unexpected productivity shocks (“surplus of energy”). According to his argument, lower income citizens barely live within their means and they cannot afford the possibility of a negative productivity shock, and therefore they become conservative. Meanwhile, middle-income citizens would appreciate the benefit of redistribution even after taking a productivity shock into account. I am sympathetic to Veblen’s argument and believe his observation is still valid, even outside the United States. At the same time, however, I found that there is little micro-foundation for his argument. Especially in a modern democracy where the voting cost is minimal, we cannot argue that every lower income class lives at the boundary of their constraints; even if there are some, the number of low-income citizens on that boundary should be small. Then it is possible for a marginal number of the poor to be conservative, but it does not necessarily mean that

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7This argument is related to the theory of optimal distinctiveness, a social psychological theory asserting that an individual’s social identity is determined by the optimal balance between the desire of inclusion and the opposite desire of distinctiveness within and between social groups and situations (Brewer, 1991). However, even if this is the main channel for the low-income citizens to identify themselves as members of a larger social group, the nation, we are not sure how this desire of inclusion is maintained when a liberal political party is in power, and how it leads to the support of economic conservatism.

8One way of using this idea with the overlapping generation models could be considering the decisions about the human capital investment of which return is uncertain. It is shown that if people with sufficiently low human capital endowments are concerned about the situation where the return is not as great as they hoped, they may abstain from human capital investment (Blackburn and Chivers, 2015).

9"(t)he process of readjustment of the accepted theory of life involves a degree of mental effort... This process requires a certain expenditure of energy, and so presumes, for its successful accomplishment, some surplus of energy beyond that absorbed in the daily struggle for subsistence... The abjectly poor... are conservative because they cannot afford the effort of taking thought for the day after tomorrow... (and they are) incapable of the effort required for the learning and adoption of new habits of thought." [Veblen (1899), pp. 203–204.]

10Houtman et al. (2008) showed the working class’ economic conservatism in Belgium. In South Korea, comparing those who self-reported that they are not in the lower income group to those who self-reported that they are in the lower income group, a smaller proportion of the lower income group felt that (1) income inequality should be dealt with by the government, (2) taxes should be increased to promote a nation’s welfare and (3) the mandatory education service should be fully supported by the government (Kang, 2010).
a substantial proportion of the poor is conservative. Moreover, if we narrow down his argument to the psychological cost-benefit analysis, there is no reason for the poor to be conservative. Rather, a higher proportion of abstention from political decisions should have been observed (Rosenstone and Hansen, 1993) or their attitude should be related to social and cultural conservatism, not economic conservatism (Lipset, 1959, 1981).

One possible way of completing this project would be to take positional externality into account. A positional good is defined as “one whose utility depends strongly on how it compares with others in the same category” (Frank, 2008). Positional goods do not necessarily mean conspicuous goods but also unwilling expenditures due to the social norm or social pressure (Hirsch, 1995; Chen, 2014), various types of investment in rent seeking (Tullock, 1980), the all-pay auction (Baye et al., 1996), or the rank-order tournament (Lazear and Rosen, 1981), and expenditures as signaling devices (Ireland, 1994) can also be represented by the form of positional goods. It is well known that when positional goods and non-positional goods coexist, the negative externality of positional goods\textsuperscript{11} steers people to re-allocate more of their resources to positional goods from non-positional goods (Frank, 1985; Hopkins and Kornienko, 2004). To consider this positional concern, I explicitly include the relative position of consumption in the utility function.\textsuperscript{12} The positional externality may also depend on another dimension: social class (Gallice and Grillo, 2018), but to clearly illustrate the role of positional concern, I restrict the model as parsimoniously as possible.\textsuperscript{13}

I show that if the citizens’ utility, and accordingly, public opinion, depend on positional concern, then the right skewness of income distribution is positively related to the increased economic conservatism of the low-income group, while the increase in the income gap between groups is negatively related to it. Lupu and Pontusson (2011) found that redistribution increases in 15 advanced democracies as the dispersion of earnings in the upper half increases relative to the dispersion of earnings in the lower half. My study may serve as a theory that supports their finding.

In the sense that I posit a behavioral assumption to explain the low-income citizens’ opposition to the redistribution policy, this paper is closely related to Kuziemko et al. (2014), where they observe the LPA both in the laboratory and in a survey about a mini-

\textsuperscript{11}If one consumes positional goods more, then the utility of some other consumers decreases even though they do not change their consumption levels. See Luttmer (2005).

\textsuperscript{12}See Clark et al. (2008), who claim that the presence of relative position terms in the utility function can play a significant role in economic models of behavior in the domains of consumption, investment, economic growth, savings, taxation, labor supply, wages and migration.

\textsuperscript{13}Fairness concern is another type of other-regarding preferences that affect the demand for redistribution but not considered in this paper. For example, Galasso (2003) showed that the introduction of inequity-adverse agents increases the equilibrium level of redistribution. For the purpose of accounting for the low demand for redistribution of low-income groups, however, I do not consider the inequity aversion.
minimum wage increase. Those who earn just above the minimum wage may vote against a policy for a minimum wage increase because it could help the group just beneath them differentially, bringing the lower-level group up to their level, which they dislike. It may explain why some of the lower income citizens vote against the redistribution policy. However, this explanation only applies to the group near the margin where the new policy directly affects, and the LPA by itself cannot explain why more severe income inequality increases the economic conservatism of the poor. I take into account the idea of the LPA in an economy with a linear redistributive tax. The main results in this study are robust in modifications of the utility function representing preferences on relative rank. For example, I did not assume the first-place loving (Gill et al., 2018) as a counterpart of the LPA. If the first-place loving exists, that is, if the marginal utility of the change in rank from second place to first is greater than that from third place to second, we could consider the utility from the relative position as an inverted S-shaped odd function with zero marginal utility at the median. The main results in this study remain unaffected by this modification, and my claims can be more strongly supported by the coexistence of the first-place loving and the last-place averse. Charite et al. (2016) provide another related piece of experimental evidence that emphasizes the importance of reference points to explain why a social planner may limit redistribution from the rich, but this evidence mainly focuses on the redistribution decision by a social planner, not the demand for redistribution by the poor.

It is worth mentioning that the probabilistic voting model (Ledyard, 1984; Lindbeck and Weibull, 1987) that predicts an equilibrium such that more inequality could be associated with smaller government. This is mainly because two competing parties consider nonlinear transfers to different groups, and if the low-income and high-income groups have non-pliable preferences over the parties’ exogenous differences, political income redistribution should be targeted to groups who are swing voters. In this paper, however, I do not consider Downsian competition between political parties and exogenous differences in policy preferences, because one of the primary goals of this paper is to show the non-monotonic changes in opinion about redistribution without relying on heterogeneity in preferences. For a similar reason, I did not consider heterogeneous beliefs about the fairness of social competition and the value of effort which could lead to completely opposite tax policies in different equilibria (Alesina and Angeletos, 2005).

2 A Model

This section is composed in the following manner: I show that the standard model cannot predict ‘the observation,’ and then I show that it cannot be predicted even after
introducing productivity shocks after implementation of a new tax policy. Finally, I introduce positional concern in the utility function and show that it reasonably predicts ‘the observation,’ and furthermore, I provide a testable prediction to address ‘the dynamics.’ For the sake of simplicity, functional forms are specified similar to those in Meltzer and Richard (1981), but my propositions hold in a more general setup.

There are three types of citizens/consumers whose type is indexed by $\theta_i$, $i \in \{H, M, L\}$ with $\theta_H > \theta_M > \theta_L$. The type represents the labor productivity, that is, their output is $y_i = \theta_i l$, where $l \in [0, 1]$ is the amount of the labor supply. There is a unit mass of population. Let $P$ denote the population distribution by type, that is, $P = (p_H, p_M, p_L)$, where $p_i$ is the proportion of the citizens with $\theta_i$ and $p_H + p_M + p_L = 1$. Both $\theta_i$ and $P$ are public information. For a benchmark, assume each type is equally populated, $P = (1/3, 1/3, 1/3)$.

In a decentralized economy, or in an economy with a non-taxation government, the citizen’s preference is represented by the utility function $u_i(c_i, l_i; \theta_i)$, where $c_i$ is the level of consumption and $l_i$ is labor supply of citizen $i$. Assume that $u_i$ is increasing and concave in $c_i$, and decreasing and convex in $l_i$. For now, assume $u_i(c_i, l_i; \theta_i) = \ln(c_i) - l_i^2/2$. The solution for each citizen’s utility maximization problem is

$$\max u_i(c_i, l_i; \theta_i) = \ln(c_i) - l_i^2/2$$

s.t. $c_i \leq \theta_i l_i$.

The indirect utility function is:

$$v_i(\theta_i) = \max_{l_i} u_i(\theta_i l_i, l_i; \theta_i).$$

In this setup, $l_i^* = 1$ and $v_i(\theta_i) = \ln \theta_i - 1/2$ for all $i$. Now suppose that a redistribution policy is proposed. A proposed public policy is $((G_i), t) = (\{L, M, H\}, t)$, where $G_i \in [0, g]$ is a lump sum transfer to consumer $i$ and $t \in [0, 1]$ is a linear tax rate on income.

A consumer’s budget balance condition is:

$$c_i = G_i + (1 - t)\theta_i l_i$$

Given $t$ and $G_i$, we can find the indirect utility function as:

$$v_i(t, G_i; \theta_i) = \max_{l_i} u_i(G_i + (1 - t)\theta_i l_i, l_i; \theta_i)$$

The government’s budget condition given $((G_i), t)$ is $t \sum p_i y_i \geq \sum p_i G_i$. To make the problem simpler, assume that transfers are uniform, i.e., $G_i = G$ for all $i$. 

8
Consider that a community holds a referendum. The citizens are divided into supporters and opposers of the referendum. If the number of votes in favor of the referendum is at least as big as the number against, the proposed change is approved. To shun additional complexity of voter turnout, assume that there is no abstention. Then the citizens’ decision rule, $V_i \in \{S, O\}$, where $S$ or $O$ means that consumer $i$ becomes, respectively, a supporter or opposer, is straightforward:

$$V_i = \begin{cases} S & \text{if } v_i(t, G; \theta_i) \geq v_i(\theta_i), \\ O & \text{otherwise}. \end{cases}$$

(3)

To exclude the trivial case, consider $t > 0$ because when $t = 0$, $v_i(t, G; \theta_i) = v_i(\theta_i)$ for all $i$. For any redistribution policy, the poor will vote for the referendum, while the rich will vote against it.

**Proposition 1.** For any $t \in (0, 1)$, $V_L = S$ while $V_H = O$.

**Proof:** See Appendix.

Proposition 1 is intuitive: The poor will favor any redistribution policy, while the rich will not. The upshot I want to convey here is that the opinion of the poor regarding redistribution is opposite to that of the rich. I neither consider the optimal policy nor pose the objective of the government. Indeed, Proposition 1 is stronger in a sense that it holds for any $t$. Moreover, the status quo condition specified, $t = 0$, is not necessary.

**Corollary 1.** For any $t, t'$ with $0 \leq t < t' \leq t^*_L$, $v_L(t', G', \theta_L) \geq v_L(t, G, \theta_L)$ and $v_H(t, G, \theta_H) > v_H(t', G', \theta_H)$, where $t^*_L = \arg \max_{t \geq 0} G(t) + (1 - t)\theta_L I^*_L - I^*_L^2/2$.

**Proof:** See Appendix.

Next, following Veblen’s (1899) argument, I take “some surplus of energy” into account. If a new policy is not accepted, consumer $i$’s productivity remains at $\theta_i$. If a new policy is accepted, then in the course of implementation, each consumer’s new productivity becomes $\theta_i^a = \theta_i + \varepsilon$, where $\varepsilon$ is a random variable whose mean is zero and variance, $\sigma^2$, is finite. This random adjustment is required to capture an empirical observation that economic mobility positively associated with the policy changes (Chetty et al., 2014). This $\varepsilon$ can be—but not necessarily—understood as a productivity shock, but it may also capture a heterogeneous ability of adaptation, and “a degree of mental effort.” It could even be as minor as a heterogenous cost of learning a new tax filing code. Unless the consumers are extremely risk-averse, this random adjustment would not drastically change the result of Proposition 1.
Redefine the indirect utility function as:

\[ v_i(t, G; \theta^n_i, \epsilon) = \max_{l_i} E_{\theta^n_i} \left[ u_i(G + (1-t)\theta^n_i l_i, l_i; \theta^n_i) \right]. \]

The citizen’s decision rule is still the same. Then, for any \( t > 0 \), we can find a sufficiently small \( \sigma_\epsilon \) such that ‘the observation’ cannot be predicted.

**Corollary 2.** For any \( t \in (0, t^*_L) \), there is \( \delta_\epsilon(t) > 0 \) such that for any \( \sigma \leq \delta_\epsilon(t) \) \( V_H = O \) and \( V_L = S \).

**Proof:** See Appendix.

Proposition 1 and Corollaries 1 and 2 reiterate our commonsense: Any redistribution policy, even if it may bring some uncertainty after implementing it, will be supported by the poor and opposed by the rich. Another property we can obtain from this setup is that if the productivity shock is large enough to make the poor vote against the referendum, the middle and the rich will also vote against it.

**Proposition 2.** For a sufficiently large \( \sigma_\epsilon > 0 \) such that \( V_L = O \), \( V_M = V_H = O \).

**Proof:** See Appendix.

That is, if the poor do not prefer a redistribution policy due to the high productivity shock associated with the policy implementation, the middle and above, who will be less benefited than the poor, will also have the same opinion. Though we can create some extreme situations to meet Veblen’s (1899) argument, this can only mean that all income classes vote against a proposed policy. There is evidence that a high tax rate is positively associated with a higher chance of economic mobility (Chetty et al. (2014)), so it makes sense to introduce a way to disturb an existing relative rank. However, the massive productivity shock by itself can hardly be supported as a reason for the low demand of the poor for redistribution. Throughout this paper, I will assume that productivity shock exists but it is substantially small.

Now, consider a positional concern by replacing the utility function \( u_i(c_i, l_i; \theta_i) \) with:

\[ u_i(c_i, l_i, F(c_i); \theta_i, \alpha), \]

where \( F(c) \) is a cumulative distribution function of population mass at consumption level \( c \), and \( \alpha \in [0, 1] \) is a weighting parameter that captures the degree of positional concern. Assume the utility function is given as:

\[ u_i(c_i, l_i, F(c_i); \theta_i, \alpha) = (1 - \alpha) \left( \ln(c_i) - l_i^2/2 \right) + \alpha \psi(F(c_i)), \]
where $c_i = \theta_i l_i$ and $\psi : [0, 1] \rightarrow \mathbb{R}$ is an increasing concave function with $\psi(1/2) = 0$. Note that $\alpha$ captures how seriously consumers are concerned for the relative rank of their consumption. The previous model is a special case of this model when $\alpha = 0$. If $\alpha = 1$, all citizens’ utility is governed by the relative rank of their consumption and they will simply oppose any redistribution policy due to the concavity of the utility.

It is worth separating this positional utility with the Keeping-Up-with-the-Joneses (KUJ) utility, one of the frequently used reference-dependent utility functions. The KUJ utility function may be understood as a special variation of this function, which can be shown as:

$$u_i(c_i, l_i, R(c_i); \theta_i, \alpha) = (1 - \alpha)(\ln(c_i) - l_i^2/2) - \alpha(c_i - R(c_i))^2,$$

where $R(c_i)$ is a comparison point, often described as a mean or median of the consumption distribution. The KUJ utility is not a special case of the positional utility functions as it lacks one important feature of positional concern—positional competition. Even at the highest income level, people compare their positions with others in the same category, and a very small positive deviation from the cohort will make one better off; at the same time a small deviation will make others worse off. The models with the positional utility predict “deviations” from the consumption level of the comparable group. However, the KUJ utility decreases as their decision deviates from the comparison point, and all the models with the KUJ utility predict “reversion” to the comparable consumption level. This limits the possibility of incorporating the feature of positional competition.

Note also that utility from the relative rank is represented by an increasingly concave function with zero utility at the median. This captures the findings that the marginal disutility of the change in rank from second-to-the-bottom to the very bottom is greater than that from third place to second; that is, it shows the last-place aversion (Kuziemko et al., 2014). We may also assume for the first-place loving that the marginal utility of the change in rank from second place to first place is greater than that from third place to second (Gill et al., 2018) by considering an inverted S-shaped odd function with zero marginal utility at the median. When we modify the utility function in this manner the main results in this study remain unaffected or are more strongly supported.

Equilibrium can be described in the manner of a symmetric Bayesian Nash Equilibrium. Each citizen, with a belief of consumption distribution, makes a decision on labor supply, and then the equilibrium allocation is consistent with the belief. It is reasonable to start with the belief that the consumption distribution is also described by $P = (p_H, p_M, p_L)$, and indeed it constructs an equilibrium. They do the same exercise to calculate the equilibrium labor supply for the case when the redistribution policy is implemented. Then they vote for or against the policy if accepting it makes them better or worse off, respectively.
**Proposition 3.** There exists a pair $(t, \alpha) \in [0, 1]^2$ such that $V_H = V_L = O$ and $V_M = S$ with a sufficiently small productivity shock.

**Proof:** See Appendix.

The basis of Proposition 3 is as follows: Instead of continuous productivity shock, consider that $\epsilon$ has two possible values, $\epsilon$ and $-\epsilon$, with equal probability. Assume that $\epsilon$ is small enough that it does not raise economic mobility across initial types, that is, $\theta_L + \epsilon < \theta_M - \epsilon$. For either the rich or the poor, new productivity shocks, no matter how small they are, give them the possibility of losing their current position with a 50 percent chance. Of course, a positive shock will give them a chance to keep the current consumption rank, but the marginal disutility of losing a current rank is greater than the marginal utility of keeping a current rank, which is zero. As for the poor, for example, the current relative rank of consumption is $p_L$, but after a new policy is implemented, half of the poor will have the relative rank of $p_L / 2$ and the other half will have the relative rank of $p_L$. Even though the marginal gain of accepting the redistribution policy is positive for the poor, it is possible for them to vote against the policy when the expected marginal disutility of losing the current rank from $p_L$ to $p_L / 2$ is greater than the marginal gain. Meanwhile, the citizens with $\theta_M$ will be less affected by productivity shock because they will be, by and large, in the middle even after the new policy is implemented. Specifically, their current relative rank is $p_L + p_M$, but after a new policy is implemented, the half of the consumers with $\theta_M$ will have the relative rank of $p_L + p_M / 2$. Though this brings some disutility, its magnitude is much smaller than that of the lower income citizens due to the concavity of $\psi(F(c))$.

Table 1: An Example of ‘the Observation’

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Under a specific tax rate shown in the first row, $V_i = O$ when citizens with $\theta_i$ oppose a proposed redistribution in equilibrium, and $V_i = S$ when they support it, $i \in \{H,M,L\}$. $P, \Theta, \epsilon, \alpha$ are assumed to be $(1/3, 1/3, 1/3), (0, 9, 1, 2), 0.01, 0.2, 0.2$. When the income tax rate varies from 0.14 to 0.24, the low-income citizens do not want redistribution, while the middle-income citizens do.

Table 1 exemplifies a set of parameters that supports ‘the observation’ under the above simplified setup with $P = (1/3, 1/3, 1/3), \Theta = (0.9, 1, 2), \epsilon = 0.01$ and $\alpha = 0.2$. I also set $\psi(F(c)) = \log(F(c))$. When the tax rate varies from 0.14 to 0.24, the low-income citizens oppose a proposed redistribution policy, but the middle-income citizens support it in equilibrium.
Note that the magnitude of productivity shock, or ability of adaptation, is not a main driving force yielding the desirable prediction because the relative rank can be proportional to the size of the population even when a productivity shock is sufficiently small. We cannot explain ‘the observation’ by simply adding a small productivity shock in a standard model (Corollary 2). With a sufficiently large productivity shock, the model without consideration of positional concern unilaterally predicts that there would be no demand for redistribution (Proposition 2). In the example shown in Table 1, I set $\epsilon = 0.01$, but any positive number below 0.1 will yield the same results.

3 Explaining ‘The Dynamics’

Another beauty of this model is that it helps us to understand why the lower income citizens exhibit more economic conservatism as income inequality becomes more severe. In particular, this model can provide a testable prediction of economic conservatism regarding how income inequality gets more severe. Although income inequality arises in a more complex way in real-life situations, there are basically two orthogonal cases in which income inequality gets more severe in the model: when the income gap between groups gets larger and when the proportion of lower income citizens gets larger while higher income citizens gets smaller. In my model, the former can be captured by the mean-preserving spread of $(\mu_L, \mu_M, \mu_H)$ and the latter by the skew of $(p_H, p_M, p_L)$. The Gini coefficient is a well-known measure used to capture income inequality, but it is silent about how changes in income inequality arose (See Figure 1.) The blue lines in both graphs show the Lorenz curves with $P = (1/3, 1/3, 1/3)$ and $\Theta = (0.6, 1, 1.8)$ and the red lines show changes in the Lorenz curve due to different parameters. On the left, $\Theta$ is changed from $(0.6, 1, 1.8)$ to $(0.43, 1, 2.14)$, while on the right $P$ is changed from $(1/3, 1/3, 1/3)$ to $(6/15, 5/15, 4/15)$. Even though the two changes in income inequality yield almost similar Gini coefficients, a larger set of parameters supports ‘the dynamics’ with the type of changes on the right if positional concern is the main cause of the economic conservatism of the poor. Let $P'$ denote $(p'_H, p'_M, p'_L)$, where $p'_H \leq p_H$ and $p'_L \geq p_L$. That is, the proportion of the high (low) income citizens decreased (increased) in $P'$. On the other hand, let $\Theta' = (\theta'_L, \theta_M, \theta'_H)$, where $\theta'_L = \theta_L - \delta$ and $\theta'_H = \theta_H + \delta$ for some $\delta \in (0, \theta_L)$.

Proposition 4. Define $A_{P, \Theta} = \{(t, \alpha) \in [0, 1]^2 | V_H = V_L = O\}$ for a given $P$, $\Theta$, and a sufficiently small $\epsilon$. For any $P'$ and $\Theta'$, $A_{P, \Theta} \subset A_{P', \Theta'}$.

Proof: See Appendix.

14Of course any linear combination of the two scenarios could increase income inequality, which is indeed more likely in real-life situations.
Figure 1: Changes in Income Inequality: Two Lorenz Curves

Blue lines in both graphs show Lorenz curves with $P = (1/3, 1/3, 1/3)$ and $\Theta = (0.6, 1, 1.8)$. The red line on the left is a Lorenz curve with $P = (1/3, 1/3, 1/3)$ and $\Theta = (0.43, 1, 2.14)$, while the red line on the right is with $P = (6/15, 5/15, 4/15)$ and $\Theta = (0.6, 1, 1.8)$. (Left) Income inequality becomes more severe as the income gaps between types get larger. (Right) Income inequality becomes more severe as the proportion of the low (high) type gets larger (smaller). Even though the two changes in income inequality look similar, hence yield similar Gini coefficients, a larger set of parameters supports ‘the dynamics’ with the changes in proportions.

In the sense that the model with positional concern can explain ‘the observation’ only under a specific set of parameters, the prediction from Proposition 3 is, at best, a description of one snapshot of the phenomenon. Although some of the low-income citizens do not want redistribution, others of them still want it. Since each citizen may have different $\alpha$ and risk preferences, even if positional concern were to be the main cause of the observation, I can only interpret that some citizens’ $\alpha$ fall within the $A_{P, \Theta}$. Therefore, it is important for us to know whether the model fits with a larger set of parameters when income inequality grows without changing the functional form of utilities. I claim in Proposition 4 that if the changes in right-skewness yield more of the low-income citizen’s economic conservatism but the mean-preserving spread of the income distribution yields less of it, then positional concern could be the driving force behind ‘the dynamics.’

The intuition behind Proposition 4 is fairly straightforward. Even if the income gaps or income-generating productivity gaps across types get larger, the expected utility changes from the relative rank would remain the same. At the same time, the lower income citizens could expect more marginal utility gain from redistribution because they would pay less taxes and the high-income citizens would pay more. That is, the lower income citizens may enjoy a larger redistribution in absolute terms with the same expected marginal disutility of losing the current relative position. This implies that a smaller set of parameters will support ‘the dynamics.’ It is the opposite with changes in the propor-
tion of the population distribution. When the income distribution is more concentrated at the lower income level, the lower income citizens would more likely vote against the redistribution policy. The marginal benefit of redistribution in absolute terms is getting smaller because the lump sum transfer is evenly distributed to the citizens with $\theta_L$, while the government’s revenue for the transfer comes from the smaller proportion of the population with $\theta_H$. The marginal cost of implementing the new policy is getting larger for the low-income group because the expected marginal disutility of receiving $-\epsilon$ is larger.

Figure 2: Opposite Predictions from Changes in Income Inequality

The x-axis and the y-axis in each graph represent the degree of positional concern, $\alpha$, and the income tax rate, $t$, respectively. The shaded areas (in both yellow and red) represent $A_{P,\Theta}$, where $P = (1/3, 1/3, 1/3)$ and $\Theta = (0.9, 1, 2)$ (Top), $A_{P',\Theta}$, where $P' = (0.233, 0.333, 0.4334)$ (Bottom Left), and $A_{P,\Theta'}$, where $\Theta' = (0.8, 1, 2.1)$ (Bottom Right), respectively. The shaded areas in red represent parameter pairs that yield $V_L = O, V_M = S, V_H = O$. Each entity consists of three letters and each of them represents each type’s opinion on redistribution. For example, ‘SSO’ means $V_L = S, V_M = S, V_H = O$, which is trivially predicted by the model without positional concern.

Figure 2 illustrates how the parameter set changes with two different causes of more severe economic inequality. Each graph in Figure 2 shows a set of parameter pairs $(t, \alpha)$.
that yields public opinion which could not be captured in previous studies. The x-axis of each graph represents the degree of positional concern, $\alpha$, and the y-axis represents the income tax rate $t$. The value for $\epsilon$ is set at 0.01. The shaded areas in red and yellow represent $A_{P,\Theta}$, that is, when parameter coordinates are in the shaded area the low-income citizens would vote against a proposed redistribution. Shaded areas in red represent parameter pairs where only the middle-income citizens support the proposed redistribution. The graph on the top is generated with $P = (1/3, 1/3, 1/3)$ and $\Theta = (0.9, 1, 2)$. The bottom left graph is with $\Theta$ and $P' = (1/3 + 0.1, 1/3, 1/3 - 0.1)$, and the bottom right graph is with $P$ and $\Theta' = (0.9 - 0.1, 1, 2 + 0.1)$. As we can see, $A_{P,\Theta'} \subset A_{P,\Theta} \subset A_{P',\Theta}$.

This clear distinction brings us a testable prediction about the relationship between the changes in income inequality and the economic conservatism of the lower income citizens. Changes in the income gap will not generate more economic conservatism of the low-income citizens, but when a higher proportion of the population is at the low-income level they become more conservative.

4 Discussions

4.1 A comparison with the prospect of upward mobility

Positional concern with a small productivity shock may not be the only possible way of explaining the poor citizens' low demand for redistribution. Benabou and Ok (2001) show that the prospect of upward mobility can rationally drag down the social demand for redistribution, though the prospect of upward mobility hypothesis cannot directly explain why some of the poor demand redistribution less than the middle-income citizens do, because it always predicts that citizens whose expected income is below that of the decisive voter (in this context, the median income citizen) will support the redistribution policy. The underlying factor that drives low demand for redistribution is the strict concavity in the mobility process: If the lower income citizens believe they, or their offspring, may move upward on the income ladder more sharply than the higher income citizens move downward, then they might not want redistribution. If the prospect of upward mobility is the main driving force behind the low demand for redistribution it will yield the opposite predictions to those in Proposition 4, that is, severe income inequality due to an increase in the income gap will lessen demand for redistribution while severe income inequality due to changes in right skewness of the income distribution will increase demand.

For illustration, I provide a simplified example from Benabou and Ok (2001). Suppose that risk-neutral agents decide today between a laissez-faire scheme and complete
sharing with respect to the next period’s income, and that the latter is a sum of a deterministic function of current income and some shocks: \( y' = \sqrt{y} + \epsilon \) for all \( y \) in an interval \([0.5, 1.5]\), where \( \epsilon \sim N(0, \sigma^2) \). Assume further that the agents are equally populated in terms of their current income, that is \( y \sim U[0.5, 1.5] \) so that the average and median income is \( \mu = \int_{0.5}^{1.5} y dy = 1 \). Note that the transition function is normalized so that someone with income equal to the average, \( \mu = 1 \), maintains the same expected income level tomorrow \( (\mu' = E[y'] = \sqrt{1} = 1) \). Everyone will expect that complete sharing gives \( \int_{0.5}^{1.5} \sqrt{y} dy = 0.9890 \) in expectation. It means that everyone whose income is initially less than 0.9781 (=0.9890^2) will see their expected income rise under complete sharing, and conversely, all those who are initially richer will experience a decline. Since the probability mass of losers is bigger than that of winners under the complete sharing scheme, or in other words, an agent with median initial income can rationally expect to be richer in the laissez-faire scheme, the median voter will oppose the complete redistribution of future income.

Considering the example above as a benchmark, I do two comparative analyses: one with the mean-preserving spread of income distribution, which is analogous to the changes from \( \Theta \) to \( \Theta' \), and the other one with the skewness change of the distribution, analogous to the changes from \( P \) to \( P' \).\(^{15}\) If the initial income is uniformly distributed on the interval \([0, 2]\) instead of \([0.5, 1.5]\), \( \mu = \mu' = 1 \) still holds. Everyone will expect that complete sharing gives \( \int_{0}^{2} \frac{1}{2} \sqrt{y} dy = 0.9428 \). It means that everyone whose income is initially less than 0.8889 (=0.9428^2) will see their expected income rise, and, conversely, all those who are initially richer will experience a decline. In the benchmark case the decisive income was 0.9781 while now it is 0.8889. It means that, even after considering some degree of risk-averseness, the likelihood that the median voter will demand future redistributions is smaller than that in the benchmark example case. Now suppose that the initial income is distributed on \([0.5, 1.5]\), with a probability distribution function of \( f(y) = 3 - 2y \) instead of \( f(y) = 1 \), that is, the proportion of agents decreases with respect to \( y \). The average income is \( \mu = \int_{0.5}^{1.5} (3 - 2y) y dy = 0.8333 \). Normalize the transition function by scaling with \( \mu \), so that someone with income equal to the average maintains the same expected level tomorrow, that is, \( y' = \sqrt{\mu y} + \epsilon \). Everyone will expect that complete sharing gives \( \int_{0.5}^{1.5} (3 - 2y) \sqrt{\mu y} dy = 0.8252 \), which is greater than the median voter’s expected income, 0.8129.\(^{16}\) Thus, the median voter, when being asked to choose either no taxation or complete sharing, will choose complete sharing. It suggests that the likelihood that the median voter will demand future redistributions is higher for a given tax rate than

\(^{15}\)It should be noted that here we consider the skewness of the initial income distribution, not that of idiosyncratic income shock as Benabou and Ok (2001) considered.

\(^{16}\)The median income is 0.7929 because \( \int_{0.5}^{0.7929} (3 - 2y) dy = 1/2 \). The median income citizen’s expected income is \( \sqrt{0.7929\mu} = 0.8129 \).
that in the benchmark example.

This illustration is not a back-to-back comparison with the model that I propose because the model in Benabou and Ok (2001) considered only two extreme cases, \( t \in \{0, 1\} \), for analytical simplicity, but it at least sheds some light on the crucial differences in predicting ‘the dynamics’ of public opinion on redistribution. Properly explaining economic phenomena, though they are seemingly puzzling, may not be of policymakers’ interests, but they should be concerned for the fundamental aspects that lead to the phenomena. If positional concern matters, utilitarian policymakers should consider ways to minimize the proportion of people crowded at the poverty level, while if an individual’s prospect of upward mobility was the key, they should think about ways to reduce income gaps. Both ways policymakers can attain a smaller income inequality, typically measured as a Gini coefficient, but as we learned, how the income distribution is shaped is as important as the level of income inequality.

4.2 Empirical/Experimental Studies

Naturally, we seek empirical evidence to test the theoretical predictions of the model. An increase in inequality due to an increase in the right-skewness of the income distribution will make it more likely to observe economic conservatism of the poor, while an increase in inequality due to an increase in the income gap between the bottom and the top of the distribution will make it less likely to observe economic conservatism of the poor. If the prospect of upward mobility, not the positional concern, is the main driving force behind the low demand for redistribution, then the signs of these relationships flip. Thus it would be ideal to find some country-level evidence of these, using data from a panel of countries on both redistribution policies and changes in income inequality. However, this is easier said than done. The main challenge is to decompose the changes in skewness with the spread of the income gap, because both happen simultaneously in reality. Figure 3 illustrates this issue on decomposition. Suppose income inequalities of one country are collected for two time periods. Unlike the model where we easily distinguish the changes in the right-skewness from the changes in the income gap by examining kinked points of Lorenz curves, changes in income inequality can be explained solely by the right-skewness or by the income gap. Of course any combination of these two can also explain the changes in income inequality. Unless a policymaker is willing to forcefully shut down one channel of inequality changes, empirical data would be exposed to the issues of under-identification.

Controlled lab experiments are a plausible alternative. What I propose is a mix-
The blue line shows a (hypothetical) Lorenz curve measured in year $t$, and the red one is a Lorenz curve in year $t'$. Although it is clear to tell that income inequality gets more severe, changes in income inequality can be explained solely by the right-skewness (horizontal arrows), explained solely by the income gap (vertical arrows), or explained by any combination of these two.

...ture of the many-player divide-the-dollar game\footnote{Since Baron and Ferejohn (1989) introduce a structural form of legislative bargaining, many-player divide-the-dollar game has been a workhorse for many experimental studies. The proposed design of experiments is similar to the design of Agranov and Palfrey (2015) who experimentally test the Meltzer-Richard model.} with random states and rank-based payments: In each round, subjects in the laboratory are randomly given their type (a constant number randomly drawn from \{0.9, 1, 2\}), and one randomly recognized player proposes the allocation of a unit of divisible budget. If the proposal is rejected by a majority then all the players will have an equally divided budget whose payoff is a multiplication of the type and share of the budget. If it is supported by a majority, then the proposed allocation is implemented, with the new type either increased or decreased by 0.05 with equal probability from the initial type. At the end of the game, they get paid additionally based on their relative rank. If the results of this experiment fit with the theoretical prediction about ‘the observation,’ one could consider two treatment sessions where each treatment modifies the values of type and the probability of each type, respectively. These treatments will tell us whether positional concern is the main driving force behind ‘the dynamics.’
5 Concluding Remarks

I showed that positional externality and a small productivity shock associated with the new policy implementation can successfully explain why some of the low-income citizens demand redistribution less than the middle-income citizens do and under what conditions the proportion of low-income citizens opposing redistribution increases with increased income inequality. If the marginal gain from redistribution in absolute terms is smaller than the expected marginal loss from a relative position, the low-income citizens may not demand redistribution. The spread of the income gap by itself does not predict such observations, but the changes in right skewness of the income distribution do.

To the best of my knowledge, this is the first trial in the literature of political economy to incorporate positional externality, although positional concern is hard to ignore and, to some degree, essential to our daily lives. The model that I consider in this paper makes many assumptions, for the sake of simplification, which could be relaxed. Especially, I assume that the labor productivity (type) is publicly observable, but as Mirrlees (1971) argues, the types are more likely to be unobservable from the perspective of government. I realize that it is challenging to find the optimal taxation when households have private information about their labor productivity and positional concerns on certain goods, but it is worth investigating the effect of positional concern on optimal taxation. I also specified the shape of the utility function for positional concern. The implicit assumption by the specification is that citizens are concerned for their relative rank of consumption over the entire population, which may not necessarily be true, in general. Although it has been empirically and experimentally supported that individuals care more for their relative rank when they are in the lower rank than when they are in the middle, one might be worried if this could be applied to cases with larger populations. Besides the theoretical improvement, laboratory experiments could be conducted to test the idea of positional concern.

Appendix

Proof of Proposition 1: Our goal is to show that \( y_L^* < y_M^* < y_H^* \). If \( y_L^* < y_M^* < y_H^* \), then \( y_H^* > (y_L^* + y_M^* + y_H^*)/3 > y_L^* \), and therefore the consumers with \( \theta_H \) pay a tax more than what they receive, while ones with \( \theta_L \) pay less than what they receive. The first order condition of the maximization problem is

\[
\frac{(1-t)\theta_i}{G + (1-t)\theta_i l_i^*} = l_i^*
\]
Solving for $l_i^*$, we have $l_i^* = \frac{\sqrt{G^2 + 4(1-t)^2\theta_i^2} - G}{2(1-t)\theta_i}$ or $y_i^* = \theta_i l_i^* = \frac{\sqrt{G^2 + 4(1-t)^2\theta_i^2} - G}{2(1-t)}$. Since $\theta_H > \theta_M > \theta_L$, it immediately follows that $y_H^* > y_M^* > y_L^*$. Next, we show that $v_H(t,G;\theta_H) < v_H(t,G;\theta_H)$. From the government’s budget condition, $G(t) = t(p_H y_H^* + p_M y_M^* + p_L y_L^*) = \frac{1}{2}(y_H^* + y_M^* + y_L^*)$. Since $G(t) + (1-t)\theta_H l_H^* = \frac{1}{2}(\theta_H l_H^* + \theta_M l_M^* + \theta_L l_L^*) + (1-t)\theta_H l_H^* < \theta_H l_H^*$, $\ln(\theta_H l_H^*) - l_H^*/2 > \ln(G + (1-t)\theta_H l_H^*) - l_H^*/2 = v_H(t,G;\theta_H)$. Therefore $\max_{l_H} [\ln(\theta_H l_H^*) - l_H^*/2] \geq \ln(G + (1-t)\theta_H l_H^*) - l_H^*/2$ for any $l_H^*$. $v_H(t,G;\theta_H) > v_H(t,G;\theta_H)$. $v_L(t,G;\theta_H) \geq v_L(\theta_H)$ can be shown similarly.

**Proof of Corollary 1:** $l_L^*$ is the optimal tax level from the perspective of the low-income group. We know $t_L^* > 0$ by Proposition 1, so the statement is well defined. We want to show that citizens with $\theta_H$ want zero taxes. By the Envelope Theorem, \[ \frac{\partial v_H(t,G;\theta_H)}{\partial t} = -\frac{\theta_H l_H^*}{G + (1-t)\theta_H l_H^*} < 0, \] that is, their indirect utility is decreasing in $t$.

**Proof of Corollary 2:** By Proposition 1, $v_H(\theta_H) > v_H(t,G;\theta_H^*,0)$. By continuity, there exists a sufficiently small $\epsilon$ such that $v_H(\theta_H) > v_H(t,G;\theta_H^*+\epsilon)$.

**Proof of Proposition 2:** By Jensen’s inequality, for any $\epsilon$ and $\epsilon'$ with $\sigma_\epsilon > \sigma_\epsilon'$, $v_i(t,G;\theta_H^*,\epsilon) < v_i(t,G;\theta_H^*,\epsilon')$. Thus we can find a sufficiently large productivity shock such that $v_L(t,G;\theta_H^*,\epsilon) < v_L(\theta_L)$. Since $u_{<0} = 0$, by the single-crossing property, $c_M^* \geq c_L^*$, which leads $v_M(\theta_M) - v_M(\theta_M^*,\epsilon) \geq v_L(\theta_L) - v_L(t,G;\theta_H^*,\epsilon)$. Since $\sigma_\epsilon$ is large enough to have $v_L(\theta_L) - v_L(t,G;\theta_H^*,\epsilon) > 0$, $V_M = O$. $V_H = O$ is analogous.

**Proof of Proposition 3:** For a sufficiently small shock, $V_H = O, V_L = S$ when $\alpha = 0$ by Proposition 1. We also know that if $\theta_M$ is equal to or smaller than the mean productivity, $V_M = S$. See Meltzer and Richard (1981). Therefore when $\alpha = 0$, $(V_L, V_M, V_H) = (S,S,O)$. For any $a > 0$, redefine the indirect utility function at the status quo as: $v_i(\theta_i, a) = \max_{l_i} (1-a)(\ln(\theta_i l_i) - l_i^2/2) + a\psi(F(\theta_i l_i))$. First I show that Bayesian Nash equilibrium exists and $v_i(\theta_i, a) = (1-a)(\ln(\theta_i - \theta_i^2/2) + a\psi(\sum_j \theta_j, p_j)$. Under the initial belief that all other’s consumption remain unchanged, any one citizen makes the consumption-labor decision. Then the marginal benefit of labor supply is $(1-a)/\theta_i + a\psi(F(\theta_i l_i))F'(\theta_i l_i)\theta_i$ and the marginal cost of labor supply is $(1-a)/\theta_i$. In this quasilinear setup the labor supply is not distorted, that is, $l_i^* = 1$ because without considering the second term of the marginal benefit, $a\psi'(F(\theta_i l_i))F'(\theta_i l_i)\theta_i$ which is positive, the optimal labor supply decision is already binding in the support of labor supply. With considering that $l_i^* = 1$ for all $i$, it is straightforward to attain the indirect utility $v_i(\theta_i, a) = (1-a)(\ln(\theta_i - \theta_i^2/2) + a\psi(\sum_j \theta_j, p_j)$, which is consistent with the initial belief we posed. Now suppose that a redistribution policy is proposed. $v_i(t, G; \theta_H^*, \alpha, \epsilon) = \max_{l_i} E_i[(1-a)(\ln(\theta_i - \theta_i^2/2) + a\psi(F(\theta_i l_i)))$
$t(\theta^*_{i \ell}))$. Initially guess that $G + (1-t)\theta_i l_i^*$ is weakly monotone increasing so the relative rank of consumption for $\theta_L$ is $p_L$, for $\theta_M$ is $p_L + p_M$, and for $\theta_H$ is 1, respectively. Then the expected utility for positional concern would be determined by $\epsilon$, productivity shock, so it doesn’t affect individual’s optimization problem. Because the cross-partial derivative of the objective function with respect to $c$ and $\theta$ is zero, we find that $c^*$ is weakly monotone increasing in type by Topkis’ theorem, and therefore, we verify our guess. When $\alpha = 1$, it is straightforward to have $(V_L, V_M, V_H) = (O, O, O)$ unless $\epsilon = 0$ due to the concavity of $\psi(\cdot)$. Since $(V_L, V_M, V_H) = (S, S, O)$ when $\alpha = 0$, but $(V_L, V_M, V_H) = (O, O, O)$ when $\alpha = 1$, by continuity, we can find (at least locally) $a^*_M \in (0, 1)$ such that $V_M = O$ if $a > a^*_M$, and $V_M = S$ if $a < a^*_M$. We can find $a^*_L \in (0, 1)$ similarly. This proof can be done by considering $\theta_L$ sufficiently close to $\theta_M$. First note that if $\theta_M = \theta_L$, then $a^*_M = a^*_L$. When $\theta_L$ changes from from $\theta_M$ to $\theta_M - \delta$ for a small positive $\delta$, $a^*_M > a^*_L$ because $\psi(\cdot)$ is increasing and concave, $\psi'(F(c^*_L)) > \psi'(F(c^*_M))$, and it is fixed regardless of the difference between $\theta_L$ and $\theta_M$. Therefore, we can pick $\delta > 0$ such that the differences in marginal utilities from redistribution of both types is smaller than $\psi'(F(c^*_L)) - \psi'(F(c^*_M))$, which is strictly positive. Under such $\delta$, $(V_L, V_M, V_H) = (O, S, O)$ in equilibrium.

**Proof of Proposition 4:** Our first goal is to show that for any $(t, \alpha) \in A_{P, \theta}$, it belongs to $A_{P', \theta}$. $(t, \alpha) \in A_{P, \theta}$ implies that $v_L(\theta_L, \alpha, P) > v_L(t, G; \theta_L, \alpha, P)$, where $G = t(p_L y^*_L + p_M y^*_M + p_H y^*_H)$. Since $y^*_H > y^*_L$, $p_L > p_L$, and $p_H < p_H$, $\tilde{G} = t(p_L y^*_L + p_M y^*_M + p_H y^*_H) < G$. That leads a decrease in $G$ in equilibrium. Since $v_L(t, G; \theta_L, \alpha, P) \geq v_L(t, G; \theta_L, \alpha, P')$, $(t, \alpha) \in A_{P', \theta}$. Our second goal is to show that for any $(t, \alpha) \in A_{P, \theta'}$, it belongs to $A_{P, \theta}$. $(t, \alpha) \in A_{P, \theta'}$ implies that $v_L(\theta_L, \alpha, \theta') > v_L(t, G; \theta_L, \alpha, \theta')$, where $G = t(p_L \theta^*_L + p_M \theta^*_M + p_H \theta^*_H)$. Since $\theta_L > \theta_L$, and $\theta_H > \theta_H$, $\tilde{G} = t(p_L \theta^*_L + p_M \theta^*_M + p_H \theta^*_H) < G$. That leads a decrease in $G$ in equilibrium. Since $v_L(t, G; \theta_L, \alpha, \theta') \geq v_L(t, G; \theta_L, \alpha, \theta)$, $(t, \alpha) \in A_{P, \theta}$.

**References**


